The Atmospheric Boundary Layer and the "Gray Zone" of Turbulence: A critical review

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Key Points:

- The horizontal grid resolution of atmospheric models has become fine enough that models are able to partially resolve turbulent motions in the atmospheric boundary layer. This resolution regime comprises the "gray zone" of turbulence.
- The traditional parameterization methods for the representation of turbulence are no longer valid in the turbulence "gray zone".
- Due to the gray-zone problem, it is no longer the case that increases to the model resolution will necessarily improve the quality and usefulness of simulation results.
- We review the current efforts by modelers to overcome the gray-zone problems in order to provide useful simulations at high resolutions.
- We conclude that the task is far from being hopeless, and propose that extensions to the approaches being developed for this field may also prove valuable for other geophysical modeling problems.

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Abstract

Recent increases in computing power mean that atmospheric models for numerical weather prediction are now able to operate at grid spacings of the order of a few hundred meters, comparable to the dominant turbulence length scales in the atmospheric boundary layer. As a result, models are starting to partially resolve the coherent overturning structures in the boundary layer. In this resolution regime, the so-called boundary-layer "gray zone", neither the techniques of high-resolution atmospheric modeling (a few tens of meters resolution) nor those of traditional meteorological models (a few kilometers resolution) are appropriate because fundamental assumptions behind the parameterizations are violated. Nonetheless, model simulations in this regime may remain highly useful. In this paper, a newly-formed gray-zone boundary-layer community lays the basis for parameterizing gray-zone turbulence, identifies the challenges in high-resolution atmospheric modeling and presents different gray-zone boundary-layer models. We discuss both the successful applications and the limitations of current parameterization approaches, and consider various issues in extending promising research approaches into use for numerical weather prediction. The ultimate goal of the research is the development of unified boundary-layer parameterizations valid across all scales.

1 Introduction

1.1 Boundary-Layer Turbulence

The atmospheric boundary layer (ABL) occupies the lowest part of the atmosphere, where most human activities take place and where weather phenomena have significant impacts on the anthropogenic and natural environment. The ABL is in direct contact with the surface and responds to surface forcings on a time scale of about an hour (Stull, 1988). In contrast to the free troposphere, which is located immediately above, the ABL is readily identified by its highly turbulent nature, which is driven by its constant interaction with the surface. Heat, moisture, momentum and contaminants are transferred and mixed by turbulent eddies having a variety of scales, ranging from a few meters to kilometers. Only under extremely stable conditions, when surface cooling is very strong and winds are very light, does turbulence cease in the ABL.

Turbulent eddies dominate the atmospheric micro-scales (cf. Orlanski, 1975). They are associated with various atmospheric phenomena such as strong gusts, pollutant dispersion, frost and fog that have significant social and economical impacts. The largest turbulent structures have scales on the order of the ABL height (about 1-3 km), while the smallest structures are dissipated at a few millimeters.

The convective ABL (CBL) commonly occurs during daytime over continental land, and is characterized by a surface that is warm compared to the air immediately above, resulting in strong surface heat fluxes. Such fluxes give rise to buoyant updraft motions, similar to warm Rayleigh-Bénard structures, called thermals, which are convective eddies extending from the surface to the top of CBL. They are associated with the peak of the energy containing scales shown in Fig. 1. The thermals are transitory structures that can move as they evolve. They break up to form smaller eddies so that their energy cascades from scale to scale through a continuous spectrum of eddy size called the "inertial sub-range" of turbulence until the Kolmogorov scale is reached and the energy is dissipated (cf. Fig. 1).

Supplementing the thermal production of turbulence, mechanical production of turbulence results from the wind shear in the ABL (e.g. due to the fact that wind "vanishes" at the surface), and this can also affect the structure and turbulent transfer in the ABL. Wind shear affects the boundary layer thermals, tilting them or weakening them. Under conditions when the wind is strong or the temperature flows are small (for example in the early morning), boundary layer thermals may be organized into convective rolls

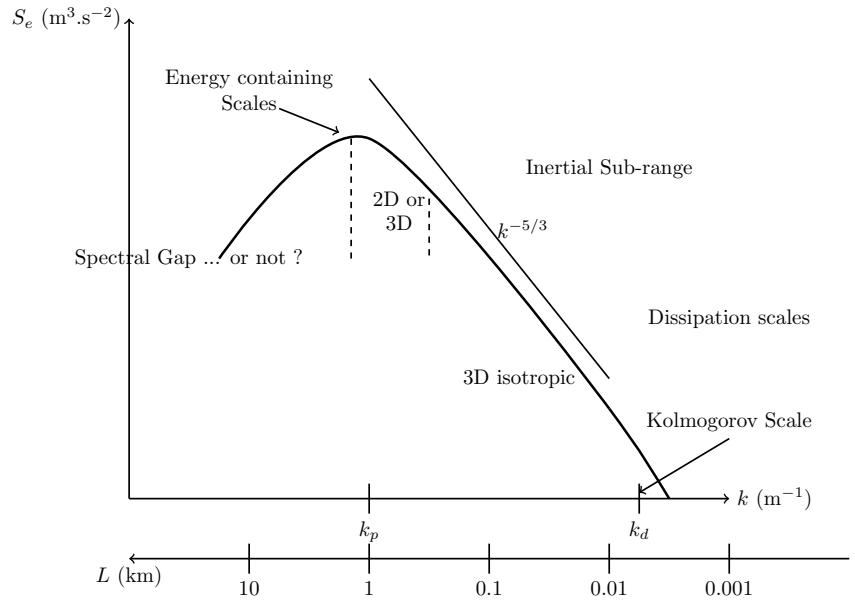

Figure 1. A schematic diagram of the turbulent kinetic energy in the CBL, plotted as a log-log graph as a function of scale. The spectral density of turbulent energy (S_e) is shown as a function of wave number k, and of the corresponding length scale $l = 2\pi/k$.

or cloud streets, which are quasi-linear two-dimensional structures (Young et al., 2002). However, under strong surface heating and light winds a regime of *free convection* occurs in the CBL with thermals dominating the transfers of heat, momentum and moisture from the surface to the overlying ABL and thence to the free troposphere.

The convection inside the CBL is often dry, with no latent heat release within the updrafts. However, if the moisture content is sufficient then shallow clouds (cumulus or stratocumulus) may appear at the top of the ABL where thermals reach their lifting condensation level. Deep moist convection refers to coherent turbulent motions of moist air well into the troposphere and the development of associated deep clouds such as cumulus congestus or cumulonimbus. Although shallow clouds at the top of the ABL will be of interest here, we do not discuss deep clouds in any detail, excepting in so far as we may be concerned with ensuring the appropriate interactions with initiating motions from ABL turbulence.

1.2 Turbulence modeling and the Terra Incognita

Traditionally, global models of the atmosphere use grid lengths on the order of 10 km or more, but limited-area mesoscale forecasting models may use grid lengths as low as 1 km. Thus, turbulent eddies are usually filtered out from meteorological models and the impact of turbulent transfer on the larger scale flow is parameterized through the use of boundary layer or turbulence schemes.

For modeling at relatively coarse grid lengths, which are larger than the scales of the largest eddies, the turbulence is entirely sub-grid (or filtered). The corresponding ABL parameterization schemes are designed to handle 1D vertical turbulent transfers that arise from the effects of the full spectrum of unresolved turbulent eddies. An additional shallow convection scheme may be needed to parameterize associated shallow cumulus clouds (cf. Section 3.4).

Modeling at fine grid lengths of O(10 m) occupies the regime of large-eddy simulation (LES), where models are able to resolve explicitly most of the turbulent motions. More specifically, simulations may be considered to be LES when the grid length is substantially smaller than the dominant turbulence length scales (i.e. $l_p = 2\pi/k_p$ in Fig. 1). Sub-grid turbulence is considered to be isotropic when the grid scale lies within the inertial sub-range (Fig. 1) and the dominant turbulence length scales become very well-resolved on the numerical grid (see Sullivan and Patton (2011) for example). At these resolutions sub-grid turbulent transfers are therefore 3D and the role of the sub-grid parameterization is to take account of the transfer of energy from the smallest resolved scale to the dissipation scales (k_d) across a clearly-defined inertial sub-range.

The advance of atmospheric modeling from its infancy in the 1950s to its widespread operational use today has been strongly related to the increase of available computer power. In particular, the development of high performance supercomputers has led to a significant increase of the horizontal grid resolution in numerical weather prediction. As resolution becomes finer, models start to resolve deep convective clouds. Weather centers around the world are now using high-resolution regional models for weather prediction or climate purposes. The UK Met Office runs its UK variable resolution model (UKV) with a 1.5 km grid length over the British isles (Lean et al., 2008) while Météo-France uses the AROME-France convective scale model at 1.3 km (Seity et al., 2011) alongside an ensemble system at 2.5 km (Raynaud & Bouttier, 2017). In the convection-allowing regime, deep convective structures become partially resolved and no longer occupy small fractional areas of the grid. Therefore, the use of conventional deep convective parameterizations at these resolutions becomes highly questionable and they are often switched off.

Pushing towards higher resolutions with grid lengths of O(100 m), atmospheric models become able to partially resolve the largest turbulent structures in the ABL, such as the strong thermals in the CBL. Recent attempts to run such high-resolution atmospheric models for weather prediction applications include the Météo-France 500 m grid-length AROME-airport (Hagelin et al., 2014) run in 2014 for the Single European Sky Air Traffic Research project and the UK Met Office 333 m "London model" (Boutle et al., 2015) which was operational for the 2012 London Olympics. Environment-Canada simulated the urban climate of Vancouver using a grid length of 250 m during the Vancouver 2010 Olympic and Paralympic Games (Leroyer et al., 2011).

Wyngaard (2004) first identified that when the size of the largest turbulence structures in the ABL is comparable to the model grid spacing, the fundamental assumptions behind conventional turbulence parameterizations are violated. He named this resolution regime the *Terra Incognita*, and the concept broadened to become the *gray zone* of turbulence in the mesoscale modeling community, focusing on the convective boundary layer. In the CBL gray zone, the turbulence kinetic energy (TKE) is only partially resolved, in contrast to the LES resolution regime where it is mostly resolved and in contrast to the mesoscale regime where it is fully parameterized.

This paper is organized as follows. Section 2 describes the different facets of the gray zone of turbulence and the related modeling problems. In Section 3 we present the possible solutions that have been proposed in the literature so far, followed by a discussion in Section 4. Conclusions are provided in Section 5.

2 Characteristics and challenges of the gray zone of turbulence

2.1 Definition of the gray zone of turbulence

Wyngaard (2004) first studied the terra incognita using near-surface observational data from the Horizontal Array Turbulence Study (HATS) program. The purpose of the HATS field program was to study the interaction between two scales of turbulence (re-

solved/filtered and sub-grid/sub-filtered), with the ultimate goal being the improvement of LES parameterizations. The experimental setting consisted of two horizontal cross-wind lines of sonic anemometers at two different levels. The filter operation was a filter in time, with Taylor's frozen-turbulence hypothesis being applied to convert to an equivalent spatial filter.

Wyngaard (2004) defined the "terra incognita" at $l \approx \Delta$, where l represents the dominant turbulence length scale and Δ represents the filter length scale. When considered in terms of a numerical model, the filter length must be interpreted as an effective resolution rather than the grid length directly (e.g. Ricard et al., 2013; Skamarock, 2004). The effective resolution depends on the internal diffusion of the model. For instance, a very diffusive atmospheric model may fail to resolve ABL turbulence even at hectometric grid size Δx, if its effective resolution Δ exceeds l.

Inspired by the pioneering work of Wyngaard (2004), Honnert et al. (2011) studied the characteristics of the CBL gray zone by averaging (coarse-graining) LES data from a number of well-documented case studies: the International H_2O project (Couvreux et al., 2005), the Wangara campaign (Clarke et al., 1971), the African Monsoon Multidisciplinary Analysis field campaign (Redelsperger et al., 2006), the Barbados Oceanographic and Meteorological EXperiment (P. Siebesma et al., 2004), and the ARMCu case (Brown et al., 2002) (cf. Fig. 2). The use of HATS data constrained Wyngaard's 2004 analyses to the surface layer, but the use of LES allows the gray zone of turbulence to be studied at higher levels throughout the ABL. The disadvantage is that results may become sensitive to the quality of the LES. Honnert et al. (2011) used LES data as a reference to document the transition of TKE and turbulent fluxes from the LES regime through the CBL gray zone and into the mesoscale regime. Coarse graining of the turbulent structures in the LES data produces smoother fields at hectometric scales in the CBL gray zone until the turbulent variability becomes completely sub-grid scale at the mesoscale.

Figure 2 presents horizontal cross-sections of vertical velocity at 500 m altitude (in the middle of the ABL) at different horizontal scales ranging from 62.5 m (the LES data) up to 8 km. This example was produced by coarse graining an LES dataset based on the International H_2O observational campaign (Weckwerth et al., 2004) using the Méso-NH model (Lac et al., 2018; Lafore et al., 1998). In this example, the transition between the CBL gray zone and the mesoscale occurs at around the 2 km scale, at which some weak turbulent structure can be seen. Honnert et al. (2011) demonstrate that the transition depends on the quantity under consideration: turbulent structures in the water vapor mixing ratio field occur on larger scales than those associated with the vertical velocity, in agreement with De Roode et al. (2004).

Honnert et al. (2011) considered the largest turbulence length scales l in the CBL to be represented by the sum of the ABL height z_i and the depth of the shallow cloud layer z_c. The basic idea is that the horizontal size of the largest structures is closely linked to their vertical extent. According to this scaling, Honnert et al. (2011) found the CBL gray zone to extend between filter scales of $0.2(z_i + z_c)$ to $2(z_i + z_c)$.

A complementary perspective is provided by Beare (2014), who defines an effective length scale for numerical models which accounts for the modeled energy dissipation emerging from both the discretised advection and the sub-grid schemes. Specifically the effective dissipation length scale $l_{d,\mathrm{eff}}$ is given by $l_{d,\mathrm{eff}} = 2\pi/k_{d,\mathrm{eff}}$, where:

$$k^2_{d,\mathrm{eff}} = \frac{\int_{k_0}^{k_1} k^2 S_e(k) dk}{\int_{k_0}^{k_1} S_e(k) dk} \tag{1}$$

k is the wave number and S_e is the TKE power spectrum. Beare (2014) considers a CBL gray-zone simulation to be one in which there is no clear separation between the production length scales and the model dissipation scale. In other words, there is no inertial sub-range in the model: recall Fig. 1. A similarity relationship as a function of $z_i/l_{d,\mathrm{eff}}$

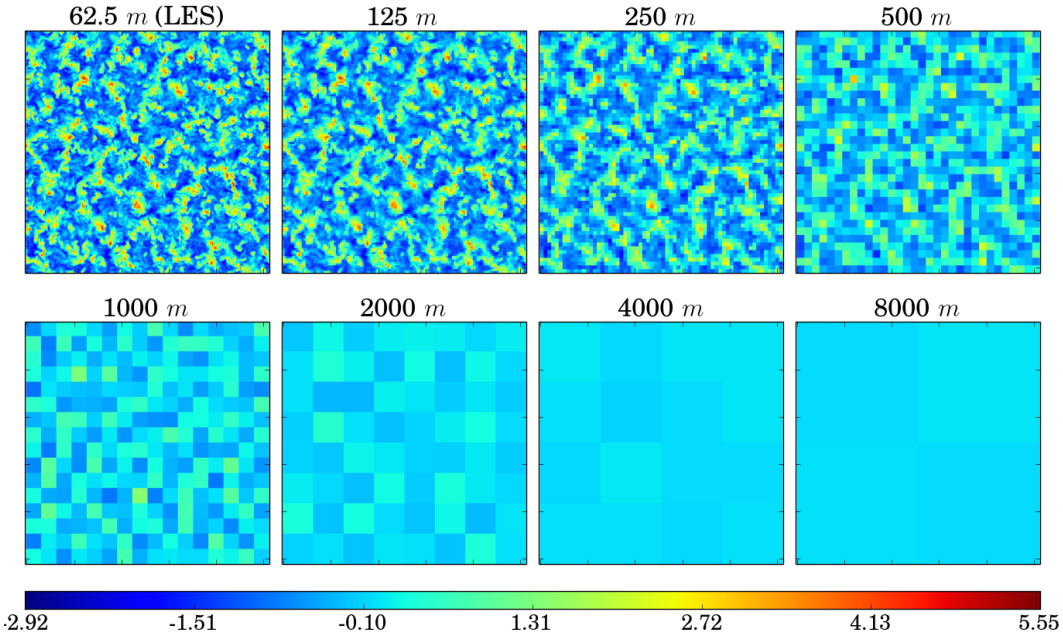

Figure 2. Horizontal cross-section of LES vertical velocity data at 500 m altitude (top left) and coarse graining of that data onto a range of scales up to 8 km. The units are ms^{-1}. Adapted from Honnert et al. (2011).

expresses the relative impact of the modeled dissipation scales on the physical production and can be used as a definition for the CBL gray zone. Beare (2014) identifies the transition between the CBL gray zone and the mesoscale regime as occurring at $z_i/l_{d,\mathrm{eff}} = 0.7$.

Figure 3 summarizes the different resolution regimes in atmospheric simulations based on the above and other related studies. The CBL gray-zone transition is determined by the dissipation length scale analysis of Eq. 1 from Beare (2014), while the LES transition is identified based on the findings of Sullivan and Patton (2011). Between the mesoscale and LES limits, we identify both a *gray zone* and a *near gray zone* (see Efstathiou et al., 2018). In the latter regime, most of the TKE is resolved ($e_{\mathrm{res}}/e_{\mathrm{tot}} \gg 0.5$) but the simulations should not be considered as LES converging because the grid length is not fine enough to present a clear inertial sub-range (see also Sullivan & Patton, 2011). The regime might also be thought of as a coarse LES simulation and most practical applications treat the regime similarly to a standard LES. However, such a treatment can have significant implications, especially in cases where the turbulence length scales are evolving (Efstathiou et al., 2018). Taking $l \approx z_i$ and $z_i \approx 1000$ m, we find that LES converging simulations can be achieved at $\Delta x \sim 20$ m while the CBL gray zone is roughly at 2 km $> \Delta x >$ 200 m.

2.2 Where is the 'truth'?

Turbulent motions are chaotic by definition. Turbulence modeling does not attempt to describe them in full detail but introduces a statistical description of the turbulence. Traditionally numerical weather prediction models simulate the Navier-Stokes equations subject to an averaging or filtering operation. The mean quantities after filtering ($\overline{f}$) are often interpreted as representing the most probable state of the atmosphere assuming that the distribution of possible sub-filter states is reasonably regular. Turbulence pa-

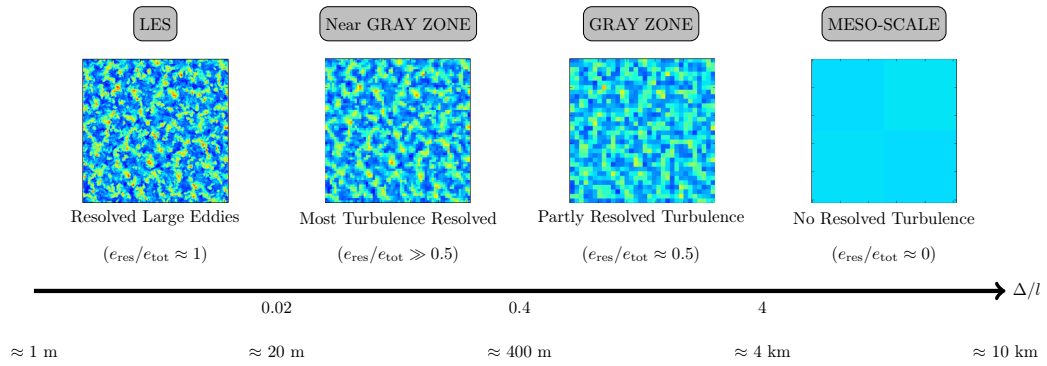

Figure 3. Schematic description of simulation regimes as a function of Δ/l, where Δ is the filter scale and l is the scale of the energy containing structures. Also shown is an estimate of typical model grid spacings. The horizontal cross-sections are taken from Fig. 2.

rameterizations for such models are often based on an ensemble average (Mellor & Yamada, 1982): i.e., an average over an infinite number of possible independent realizations of the flow. More generally, the averaging operator is assumed to fulfill Reynolds assumption (Stull, 1988, e.g., $\overline{\overline{g}\overline{f}} = \overline{g}\overline{f}$, where f and g are functions and $\overline{f}$ denotes the average of f).

An alternative to ensemble averaging is to consider the filtering to be a time or space average. This approach is taken, for instance, when researchers average LES output data in order to characterize turbulent statistics (Couvreux et al., 2010; A. P. Siebesma & Cuijpers, 1995, see also Sections 2.1 and 2.4) and to develop mesoscale parameterizations (e.g. Rio et al., 2010). If a spatial averaging scale is sufficiently large as to sample many eddies then there is often no practical difference between ensemble and spatial averaging. However, for a grid scale that is hectometric the form of the assumed averaging operator becomes crucial.

Using a space-time filter at scales of the gray zone of turbulence, model output fields should become turbulent, and partially-resolved turbulent structures appear (cf. Fig. 2). Such outputs represent one possible state of the atmosphere on the filtered scales. Real-scale experimental data represent only one possible state of the atmosphere also, and this would likely differ from the model state even if one were to have a perfect model.

2.3 Transition from sub-grid to resolved turbulence

As discussed above, turbulence in the CBL gray zone is partially resolved. Using LES data, the partitioning of turbulent energy into that which is sub-filter and that which is resolved can be computed for a given filter. The partition will depend upon the filter scale and the size of the turbulent structures. Honnert et al. (2011) considered such partitions for TKE and turbulent fluxes across the transition from the LES converging regime to the mesoscale limit in cases of free dry and cloudy CBLs. The partition function was scaled using the similarity parameter $\Delta x/(z_i+z_c)$ with Δx being the coarse-graining filter scale. Figure 4 shows such a transition curve for the TKE. The approach has also been extended to other types of ABL (Shin & Hong, 2013).

The transition curve for the partitioning of turbulent quantities across scales has become widely used as a reference tool and a test-bed for the development and testing of parameterizations for the CBL gray zone (Boutle et al., 2014; Efstathiou & Beare, 2015; Ito et al., 2015; Malavelle et al., 2014; Shin & Hong, 2015; Shin & Dudhia, 2016).

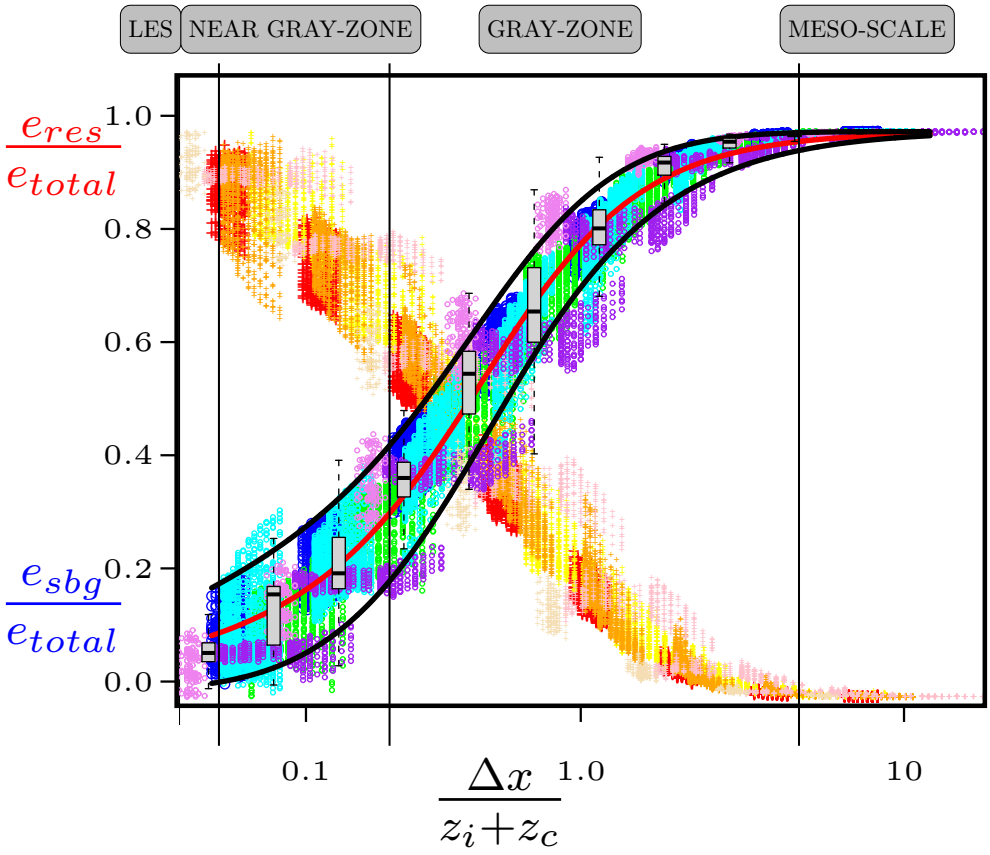

Figure 4. Functions showing the partition of the total TKE e_{total} into resolved (e_{res}) and sub-grid (e_{sbg}) parts, as a function of $\Delta x/(z_i + z_c)$ (from Honnert et al., 2011): $e_{\text{res}}/e_{\text{total}}$ is in warm colors and $e_{\text{sbg}}/e_{\text{total}}$ is in cold colors. A similarity relation was found to hold in the CBL at altitudes z between $0.05z_i$ and $0.85z_i$.

Honnert et al. (2011) evaluated the behavior of a state-of-the-art mesoscale model (Méso-NH) in the CBL by comparing simulations at different scales against the reference curve of Fig. 4. Within the CBL gray zone, the resolved turbulence was found to be too large when the model's turbulence scheme was used without its mass-flux part. The scheme did not mix the boundary layer efficiently enough, regardless of the mixing length scale parameter that was used within the scheme to calculate the diffusivity. In contrast, Honnert et al. (2011) found the resolved turbulence to be too weak when the mass-flux scheme component of the scheme was activated. This effect strongly depends on the mass-flux scheme (Shin & Dudhia, 2016). One of the mass-flux-type ABL schemes tested in Shin and Dudhia (2016) showed a strong resolved turbulence even though the mass-flux component was activated, because the mass-flux part was not large enough to estimate the vertical transport by strong updrafts.

2.4 Traditional assumptions in models of the atmospheric boundary layer challenged by the gray zone of turbulence

The results discussed in Sect 2.3 illustrate that in the transition between sub-grid and resolved turbulence, traditional assumptions made in models of the atmospheric boundary layer, either at coarse or at very fine resolutions, are no longer valid in the gray zone of turbulence.

Large-scale models assume that the filter length scale (and also the related grid length of the model) is much larger than the important turbulent length scales in the boundary layer, and that therefore the representation of turbulence in the boundary layer does not strongly depend on the resolution of the model. They additionally assume, as mentioned in Section 2.2, that turbulent transfer is represented by an ensemble average of all possible flow realizations inside each grid box and as a result only the mean effects of turbulent motion are considered. On the opposite end of the spectrum, LES models require that the inertial sub-range is well resolved and so that the sub-grid turbulence scheme depends on model resolution in straightforward ways that can be deduced from scaling arguments. In neither case, however, is there any guarantee of an appropriate scale-awareness of the sub-grid turbulence within the gray zone of turbulence.

Another important issue is that large-scale models assume that sub-grid turbulent transport is dominated by the vertical component, and are therefore one-dimensional. However, neither is the sub-grid turbulence isotropic in three dimensions as commonly assumed by LES models. Thus, the gray zone of turbulence raises issues around the extent of anisotropy.

Wyngaard (2004) rigorously analyzed the turbulent momentum fluxes in the surface ABL with data from an anemometer array. The arrangement is illustrated in Fig. 5. He showed that some production terms for turbulent fluxes that may be negligible in the LES and mesoscale limits can nonetheless be significant in the gray zone of turbulence. Such terms are associated with anisotropy of the flow. It is important to bear in mind however, that the buoyancy-driven turbulence which dominates in the middle of the CBL is more strongly uni-directional than the shear-driven turbulence which plays an important role in the surface layer.

Honnert and Masson (2014) use LES coarse-graining of idealised CBL simulations to assess the scale dependence of turbulence production terms for TKE in the CBL above the surface layer. They show that 3D dynamical production terms become non-negligible over flat terrain at resolutions finer than $0.5(z_i+z_c)$, a result which implies that for such scales then 1D parameterizations do not provide an adequate representation of the TKE. According to Honnert and Masson (2014) the turbulence is anisotropic at about $0.02 \leq \Delta x/(z_i+z_c) \leq 0.5$. This range is consistent with the analysis of Beare (2014) for defining the CBL gray-zone onset from a different perspective (Section 2.1). Interestingly, Efstathiou and Beare (2015) also related the gray-zone onset to the need for different treatments of vertical and horizontal diffusion in their sub-grid model when simulating a quasi-steady state CBL.

Moreover, in both large-scale models as well as LES models, sub-grid turbulence schemes are usually assumed to be deterministic. Transport in the CBL is characterised by a population of turbulent eddies that cover a range of scales. With increasing model resolution the largest eddies are resolved first. Assuming that a space-time filtering approach is being taken, as in most traditional large-scale models of the ABL, then the part of the eddy size distribution that remains sub-grid will become increasingly under-sampled, with few of the largest unresolved eddies being present on the scale of a grid cell. Thus, one expects to find stochastic behavior near the grid scale in the gray zone of turbulence, and the traditional assumption that the number of eddies or updrafts in each grid cell

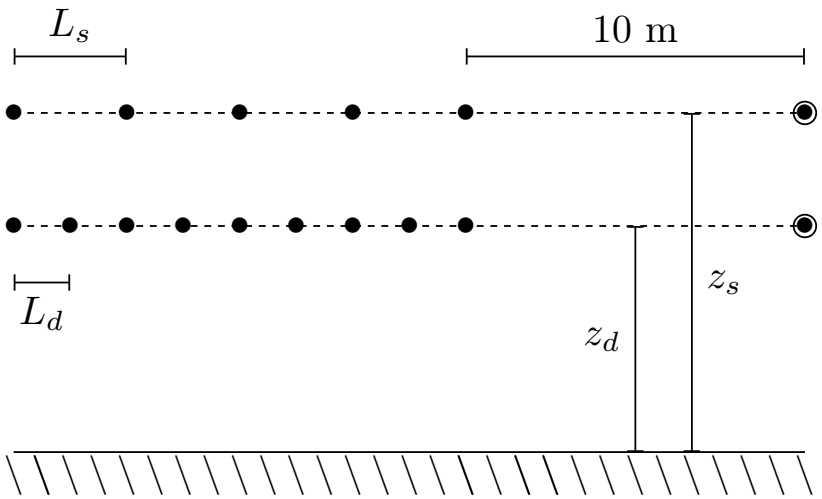

Figure 5. Arrangement of sonic anemometers in the HATS experiments. Single and double arrays are located at heights z_s and z_d above the surface, and the crosswind separation between individual sonic anemometers at each height is L_s and L_d respectively. Two reference sonic anemometers (circled) are used to monitor the possibility of flow interference among the anemometers in the s and d arrays. Adapted from Sullivan et al. (2003)

is large enough to fulfill the "law of large numbers" underlying deterministic parameterizations is no longer valid.

Other important assumptions concern the representation of non-local expressions in turbulence parameterizations. These are often formulated using mass flux approaches (Section 3.4). As resolution increases, the large non-local motions will be partially resolved within the CBL gray zone. Mass-flux schemes used in meso-scale models assume that the non-local part of the flux is attributable to these CBL thermals, that the resulting flux is stationary and that the thermals occupy a relatively small area compared to their more quiescent environment. Each model grid cell is supposed to contain both a meaningful number of such thermals and their associated compensatory subsidence. The assumption that the vertical velocity in the grid cell is zero or that the thermal fraction is negligible breaks down by definition in the CBL gray zone where the thermal length scale is on the order of the grid spacing.

2.5 Gray zone in an evolving convective boundary layer

Atmospheric models have a fixed grid length but the turbulence characteristics may change in the course of a simulation. A pertinent example is the development of a CBL that is strongly forced by surface heating, as often occurs over cloud-free land during the morning. Figure 6 shows the evolution of such a developing CBL in a case study using the Met Office Large Eddy Model (LEM) with $\Delta x = 200$, 400 and 800 m (Efstathiou et al., 2016). Shaded in gray are the times and heights where the flow is considered to be in the CBL gray zone, according to the analysis of Beare (2014). In the 800 m run the CBL remains in the gray zone throughout the simulation. In contrast, the 200 and 400 m simulations lie in the CBL gray zone only during the early CBL development, albeit with the 400 m run taking somewhat longer to transition to the coarse LES regime. Moreover, near the surface and the top of the ABL the CBL gray zone persists for longer since the turbulent length scales are affected by the presence of these boundaries to the turbulent part of the flow. Thus, we see that a simulated evolving CBL can be in dif-

ferent resolution regimes that can vary both in time and space depending on the scale of the convective structures.

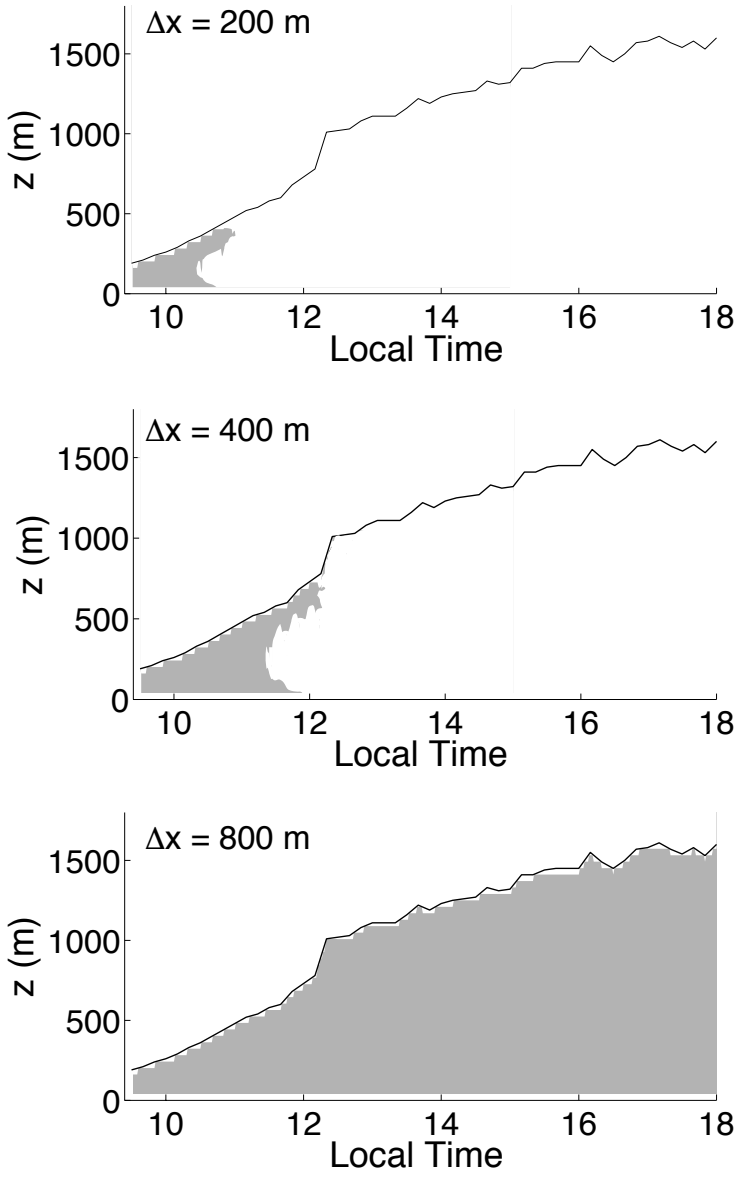

Figure 6. The time evolution of the CBL depth (black line) in a case study simulation of an evolving CBL (Efstathiou et al., 2016) using three different horizontal grid spacings. Shaded in gray color are the parts of the CBL that are considered to be in the gray zone of turbulence according to the analysis of Beare (2014).

A particular problem in gray-zone simulations of an evolving CBL concerns the spin-up of realistic levels of resolved TKE from the initial state. Efstathiou et al. (2016); Zhou

et al. (2014) and Kealy et al. (2019) have shown that spin-up is significantly delayed with coarsening resolution within the CBL gray zone. Shin and Hong (2015) also pointed out that their gray-zone CBL parameterization delayed the spin-up of resolved motions. The consequence of delayed spin-up is that temperature profiles can become super-adiabatic in response to the lack of non-local mixing that the resolved TKE would otherwise provide. Such a delay can also have significant implications when simulating the full diurnal cycle of convection, including the transition from shallow to deep moist convection (e.g. Petch et al., 2002).

2.6 From shallow to deep moist convection to synoptic-scale systems

Various properties of convective clouds and mesoscale systems in sub-kilometric models have been demonstrated to be rather sensitive to the choices made in the formulation of turbulent mixing within the gray zone of turbulence. Some good examples can be seen in the idealized modeling studies of Bryan and Morrison (2012); Craig and Dornbrack (2008); Fiori et al. (2010); Verrelle et al. (2015). Similar case studies in realistic conditions can be found in Bengtsson et al. (2012); Duffourg et al. (2016); Martinet et al. (2017); Ricard et al. (2013), while a rich statistical perspective is provided by Stein et al. (2015). The studies of Tomassini et al. (2016); Sakradzija et al. (2016) focus particularly on the interplay between boundary-layer turbulence and shallow convective clouds.

The representation of boundary-layer turbulence in numerical weather prediction models does not only interact with (shallow and deep) convective cloud, but is also closely interrelated with the representation of the land surface, the atmospheric dynamics, and microphysics (Field et al., 2017). Boundary-layer processes are important even for synoptic scale weather systems. In the mid-latitudes, boundary-layer friction provides a damping mechanism for barotropic vortices through Ekman pumping (Boutle et al., 2015). Baroclinic developments are also dampened by changes to low-level stability which can be understood in terms of tendencies of potential vorticity that are produced by turbulent mixing processes (Adamson et al., 2006; Stoelinga, 1996). By contrast, in the tropics, boundary-layer dynamics may often act to enhance synoptic-scale systems. This is well illustrated by African easterly waves, for which potential vorticity generation by boundary-layer processes can feed into the dynamics and contribute to wave growth (Tomassini et al., 2017). Moreover, boundary-layer turbulence is important in the establishment of summer time low-level jets over land which may transport high moist static energy air and feed deep convective development (Chen & Tomassini, 2015). This mechanism is particularly relevant in monsoon regions and at continental-scale precipitation margins.

3 Modeling the atmospheric boundary layer in the gray zone of turbulence

As explained in Section 2, the gray zone of turbulence is not a physical phenomenon, but rather it describes interrelated problems that arise due to the assumptions behind our current turbulence and shallow convection schemes. In this section, we consider some possible solutions that have been proposed to those problems, and their limits.

3.1 Full transport model approach

Wyngaard (2004) suggested using the full transport equations for representing the sub-grid scalar transport of a conserved scalar field c at gray-zone resolutions in the boundary layer. Without imposing the usual assumptions in mesoscale modeling he introduced a tensor form for the parameterization of the turbulent flux (f_i) of c (see Appendix A for an outline of the derivation):

$$f_i = -K_{ij} \frac{\partial \overline{c}}{\partial x_j} \tag{2}$$

where K_{ij} is a tensor form of the eddy diffusivity which is a function of a turbulent time scale, the shear tensor and the Reynolds stress. Thus, Wyngaard's 2004 model can be viewed as a generalized form of the usual diffusion approach which can account for anisotropy of the turbulence. As implied by the arguments of Section 2.4, this extension is an attractive possibility for modeling sub-grid fluxes from the LES to the mesoscale limit. The eddy diffusivity is a function of the flow and should be treated as a tensor and not as a scalar. Other elements of the full tensor may become important in the gray zone of turbulence (such as the tilting terms) since the heterogeneity of the convective structures might impose strong horizontal gradients.

Hatlee and Wyngaard (2007) first implemented the approach to study HATS data close to the surface. Kelly et al. (2009) extended the approach to the ocean surface layer by analyzing data from the OHATS (Ocean Horizontal Array Turbulence Study) observations and developed a simple parameterization for pressure fluctuation induced by moving surface waves. The full transport equations have been implemented by Ramachandran and Wyngaard (2011) and Ramachandran et al. (2013) in simulations of a convective case in the ocean. They showed that the anisotropic terms in the sub-filter flux equations can indeed become important when the grid length approaches the dominant production scales, in accordance with the HATS analyses of Hatlee and Wyngaard (2007). Therefore their model produced much better estimations of the momentum and heat fluxes compared to the standard eddy-diffusivity approach.

The full transport model apears to be a promising first approach to modeling in the gray zone of turbulence. Such an approach is expected to behave analogously to a higher-order closure scheme in the mesoscale limit with the appropriate choice of length scales (Wyngaard, 2004). However, the shortage of validation studies, and in particular the absence of a full implementation of the method accross the complete range of modelling scales, does not allow firm conclusions to be drawn on the performance or the practical applicability of the scheme.

3.2 TKE turbulence modeling

TKE-based turbulence models determine eddy diffusivities based on the magnitude of sub-grid TKE, e, specifically:

$$K_c = C_c l_m \sqrt{e} \tag{3}$$

where C_c is a constant which may depend on the variable c of interest, while l_m is the mixing length. l_m may be set using the CBL height in mesoscale models, but is based on the grid spacing in LES applications of the approach. The sub-grid TKE itself is obtained by solving its prognostic equation:

$$\frac{\partial \overline{e}}{\partial t} = -\left(\overline{u_i} \frac{\partial \overline{e}}{\partial x_i} + \frac{\partial \overline{u_i' e}}{\partial x_i} + \frac{1}{\rho_0} \overline{u_i' \frac{\partial p'}{\partial x_i}} - \nu \frac{\partial^2 \overline{e}}{\partial x_i^2} \right) - \overline{u_i' u_j'} \frac{\partial \overline{u_j}}{\partial x_i} + \beta \overline{u_3' \theta'} - 2\nu \overline{\left(\frac{\partial u_j'}{\partial x_i} \right)^2} \tag{4}$$

where θ is the potential temperature, p is the pressure, ν is the molecular diffusivity and β is the buoyancy parameter. Other symbols have been already introduced. The first (in parentheses) term on the right hand side describes the tendency of e due to large scale advection, turbulence, pressure gradient correlations and molecular diffusion, the second and third terms represent the production of turbulence by wind shear and buoyancy respectively and the last right-hand side term is the dissipation of e.

3.2.1 Pragmatic approaches over complex terrain

Turbulence parameterizations for atmospheric models have been developed based on assumptions that are, strictly speaking, only valid for horizontally homogeneous and flat terrain, and may not be suitable for complex terrain. For example, Monin-Obukhov similarity theory is commonly used to compute surface fluxes and assumes horizontally

homogeneous fluxes from the surface into the boundary layer. In complex terrain, Arnold et al. (2012) recommends as a first approach the use of fully prognostic three-dimensional TKE schemes for grid spacings between 100 and 300 m.

Beljaars et al. (2004) proposed a parameterization of turbulent orographic form drag that takes into account the model resolution and is used at ECMWF. However, while there are studies of the behavior of orographic drag in the gray zone of deep convection (5 km resolution), (Sandu, ECMWF Newsletter 150) there are none as yet at the hectometric scales. At hectometric scales, it is not well understood which part of the drag should be taken into account through an explicit parameterization of orographic drag and which part by the turbulence scheme. We note that the model of the Met Office does not include an orographic drag contribution at such scales. Moreover, the theoretical background of the processes involved is not well understood even at mesoscales (see Sandu, ECMWF Newsletter 150). Hence, analysis of the problems in representing orographic drag in the gray zone of turbulence is more difficult than an analysis based on the dynamic production of TKE in the turbulence scheme.

Over complex terrain in the CBL gray zone, the full three-dimensional effects have been found to be important in the shear production term for TKE (Arnold et al., 2014; Goger et al., 2018). Goger et al. (2018) therefore propose an extension of the 1D prognostic TKE equation used in the COSMO (COnsortium for Small-Scale Modeling) model turbulence scheme because that scheme otherwise underestimates the TKE. The 1D form considers only the contributions to shear production from vertical gradients of horizontal winds, but Goger et al. (2018) supplement this with a further contribution of

$$\left.\frac{\partial \overline{e}}{\partial t}\right|_{\text{shear}} = (C_s \Delta x)^2 \left[\left(\frac{\partial \overline{u}}{\partial x} \right)^2 + \left(\frac{\partial \overline{v}}{\partial y} \right)^2 + \frac{1}{2} \left(\frac{\partial \overline{u}}{\partial y} + \frac{\partial \overline{v}}{\partial x} \right)^2 \right]^{\frac{3}{2}} \tag{5}$$

where C_s is chosen to be the Smagorinsky constant (see Section 3.3). This extension was tested in simulations over the Alps for a grid length of 1.1 km and had beneficial effects. The verification indicated improvement in the TKE on the slopes, which suggests that the addition of 3D effects is particularly suitable for inclined surfaces.

3.2.2 Adaptive length scales

In order to incorporate scale-awareness (Section 2.4), various authors have attempted to develop approaches for the gray-zone of turbulence that are based on rethinking the mixing length that is used in TKE-based approaches (Eq. 3) or other semi-empirical length scales used in higher-order turbulence models. Ito et al. (2015) for example, has proposed an extension of Mellor-Yamada-Nakanishi-Niino (MYNN) model for the gray zone of turbulence. The MYNN model is a higher-order turbulence closure designed for 1D mesoscale applications (Nakanishi & Nino, 2009). The sub-grid TKE is predicted using an empirical length scale to parameterize various terms. In the extension the length scale is modified in order to hold the TKE dissipation invariant to the grid resolution. To partition the TKE into appropriate resolved and sub-grid contributions the extension also considers the partition function proposed by Honnert et al. (2011) (as discussed in Section 2.3). Horizontal diffusion based on Ito et al. (2014) is also included in order to take account of anisotropy (Section 2.4). Ito et al. (2015) showed that a CBL gray-zone simulation employing this extension was able to realize reasonable vertical transports.

Kitamura (2015) used a coarse-graining approach on LES data from a CBL simulation in order to estimate the length scale dependence on grid spacing, assuming the form of a TKE-based Deardorff (1980) model for the turbulent fluxes. Notably the estimated length scale was found to depend upon both the horizontal and vertical grid spacings. Kitamura (2016) implemented the resulting mixing length formulations in a modified Deardorff (1980) model, which improved the representation of the vertical heat flux and the magnitude of the resolved convection in the CBL gray zone.

Zhang et al. (2018) blended between the sub-grid turbulent mixing length scales that are appropriate for the LES and mesoscale limits to create a grid-scale-dependent 3D TKE scheme. The scheme includes a non-local component in the vertical buoyancy which is also down-weighted by a blending function (cf. Boutle et al., 2014) depending on the resolution regime. The blended approach was implemented in WRF and exhibited improved behaviour in comparison with a conventional TKE scheme.

Kurowski and Teixeira (2018) also proposed to pragmatically merge the mixing lengths from LES and NWP formulations to obtain a mixing length for intermediate scales:

$$\left(\frac{1}{l_{BL}}\right)^2 = \left(\frac{1}{l_{1D}}\right)^2 + \left(\frac{1}{l_{3D}}\right)^2 + \left(\frac{1}{l_s}\right)^2 \tag{6}$$

where l_{3D} is Deardorff LES mixing length (Deardorff, 1980), l_s is a surface mixing length (see Kurowski & Teixeira, 2018) and l_{1D} is the large scale NWP mixing length from Teixeira and Cheinet (2004). In their formulation, the mixing length is smaller than the smallest of the three components. Their merged mixing length does not explicitly depend on resolution, but in practice it increases with increasing grid size until the mesoscales.

3.2.3 Two turbulence kinetic energies

A related approach has been proposed by Bhattacharya and Stevens (2016) who introduce two turbulent kinetic energies in order to distinguish between the energy contained in large eddies spanning the CBL and that within eddies that are sub-grid with respect to the vertical grid spacing. The two energies are conceptually linked via the turbulent energy cascade. Bhattacharya and Stevens (2016) formulated distinct length scales to describe mixing and dissipation associated with each energy. However, the problem remains of how to divide the energy due to the boundary-layer-scale eddies into resolved and unresolved parts. The approach is yet to be tested in a weather or climate model.

3.3 Extending the Smagorinsky-Lilly scheme into the gray zone of turbulence

The Smagorinsky-Lilly (Lilly, 1967; Smagorinsky, 1967) scheme is a widely-used standard for large-eddy simulations of many and various engineering and geophysical flows. Scalar fluxes are represented by:

$$f_i = -K_c \frac{\partial \overline{c}}{\partial x_i}, \tag{7}$$

as described in Appendix Appendix A (Eq. A3). The eddy diffusivity is expressed as

$$K_c = l_t^2 \mid \overline{S} \mid /\mathrm{Pr} \tag{8}$$

where Pr is known as the Prandtl number, $\mid \overline{S} \mid$ is the modulus of the shear tensor $\overline{S}_{ij} = (\partial \overline{u_i}/\partial x_j) + (\partial \overline{u_j}/\partial x_i)$, and l_t is the turbulence mixing length. The specification is completed by choosing the mixing length to be $l_t = C_s \Delta$ where C_s is known as the Smagorinsky constant. Following the analysis of Lilly (1967) it is often set to 0.17 although different values up to 0.23 have been suggested and used in atmospheric models. The Smagorinsky scheme acts in all three directions with the same eddy diffusivity. Comparing to Eq. 2, the scheme is an approximate form of the full turbulent stress tensor model, valid when the full turbulent stress tensor is assumed isotropic, such that $K_{ij} = K_c \delta_{ij}$.

3.3.1 Bounding approach

Efstathiou and Beare (2015) showed that the standard Smagorinsky scheme becomes too diffusive in the CBL gray zone. Therefore, in order to reduce the over-damping effect arising from the increase in mixing length l_t with horizontal resolution Δx, a modification was made in an attempt to conserve the effective diffusivity of the flow across

different grid lengths. As a first approximation, the vertical Smagorinsky diffusivity profile was bounded so that values could not exceed those produced by a 1D mesoscale approach. The horizontal diffusion was handled by a 2D closure and allowed to vary in order to account for anisotropy of the flow at CBL gray-zone resolutions. This bounding approach was able to match the energetics of the coarse-grained fields across the transition from the LES to the mesoscale regime in a quasi-steady state CBL.

3.3.2 Dynamic Smagorinsky

The standard Smagorinsky approach is designed for the LES regime and assumes a clear scale separation with the presence of a clear inertial sub-range (Section 2.4). The idea behind a dynamic model is to treat C_s as a flow-dependent variable, which can be estimated by comparing the resolved flow against the same flow filtered onto a coarser "test" scale. The idea can also be extended through comparison of the resolved flow against that at two different filtered scales in order to estimate a flow-dependent and scale-dependent C_s. The aim of such a scale-dependent dynamic model is to respect the characteristics of the turbulence spectrum without necessarily requiring the resolved flow to lie within the inertial sub-range. Hence, it is a promising extension of Smagorinsky that is well suited to coarse LES resolutions (e.g. Kleissl et al., 2006; Mirocha et al., 2013) and perhaps even to CBL gray-zone resolutions.

Efstathiou et al. (2018) modified and implemented a scale-dependent, Lagrangian-averaged dynamic Smagorinsky sub-grid scheme based on Bou-Zeid et al. (2005) into the Met Office Large Eddy Model. Extending an earlier study by Basu et al. (2008), they found the approach to perform well for an evolving CBL in capturing the resolved turbulence profiles in comparison with coarse-grained LES fields, especially in the *near gray-zone* regime (Fig. 3). However, such a dynamic approach reaches a limit of applicability if the test filter is required to sample the flow at a scale for which the turbulence is not adequately represented by the model.

One way around this issue could be the use of the Dynamic Reconstruction Model of Chow et al. (2005) which attempts to reconstruct the smallest resolved scales and uses those to dynamically derive the sub-grid mixing length. Simon et al. (2019) tested this approach to simulate a quasi-steady CBL at gray-zone resolutions and found significant improvement over conventional schemes and especially compared to the standard Smagorinsky scheme.

3.4 Modifying boundary layer 1D non-local parameterizations

CBL thermals (cf. Section 2.4) are manifestations of non-local turbulence, and are responsible for the development of a zone of counter-gradient fluxes at the top of the CBL which is ill-represented by an eddy diffusivity form (Eq. 3).

In mesoscale models, the turbulent transport from the surface to the top of the ABL by convective thermals can be parameterized by the use of an additional counter-gradient term (Deardorff, 1972) so that,

$$f_c = -K_c \left(\frac{\partial \overline{c}}{\partial z} - \gamma \right) \tag{9}$$

where f_c is the turbulent flux of c and γ is the counter-gradient term. More complex parameterizations have been based on the transilient matrix (Stull, 1984)) or the mass-flux scheme (Cheinet, 2003; Hourdin et al., 2002; Pergaud et al., 2009; Rio et al., 2010; A. P. Siebesma et al., 2007; Tan et al., 2018). In a mass-flux scheme the turbulent flux is expressed as

$$f_c = -K_c \frac{\partial \overline{c}}{\partial z} + M_u (c_u - \overline{c}) \tag{10}$$

where M_u is the mass-flux associated with the ABL thermals, and c_u is the mean value of c inside the thermals. The second term on the right-hand side represents the transports by coherent thermal plumes whereas the first term is expressed in eddy diffusivity form and represents the contributions from smaller-scale more-localized eddies (Fig. 7). This mass flux approach also lends itself naturally to extensions that treat shallow boundary-layer clouds.

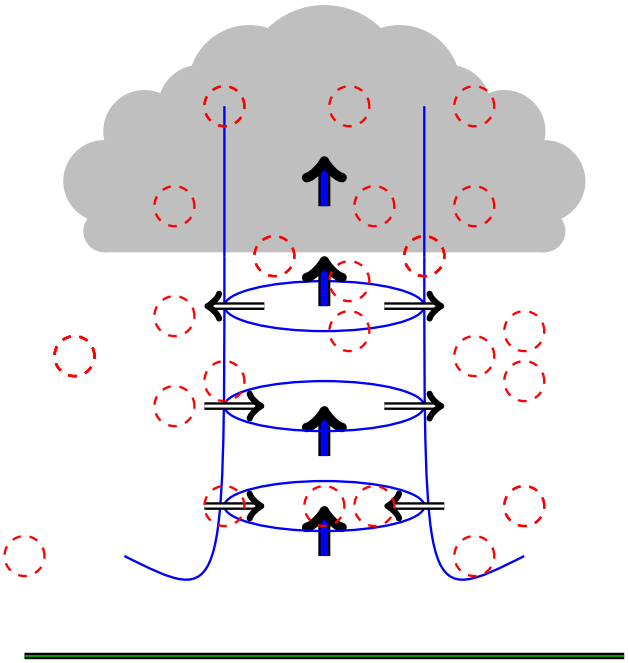

Figure 7. Schematic diagram of small local eddies (red dashed circles), contrasted against a non-local thermal (blue tube) which extends from the surface (green) to the cloud layer (in gray).

Representations of the form of Eqs. 9 and 10 are designed for mesoscale models but the split provides an interesting starting point for possible gray zone treatments of turbulence. As resolution increases the large non-local motions will be partially resolved within the CBL gray zone for $\Delta \sim z_i$ but the small eddies might remain purely sub-grid. With this point in mind, the adaptation of mesoscale models to the CBL gray zone could be achieved by revisiting traditional non-local ABL schemes.

A mass-flux scheme used at the mesoscales assumes that a non-local flux is created by the CBL thermals. This flux is assumed to be stationary and is created by several thermals which occupy small areas compared to their more quiescent environment. Each model grid cell is supposed to contain both a meaningful number of updrafts and their associated compensatory subsidence. Such assumptions break down by definition in the CBL gray zone where the thermal length scale l is of the order of the grid spacing Δx (Section 2.4). Related issues have been studied in the context of the mass-flux representation of deep convective clouds and are discussed by Arakawa et al. (2011); Arakawa and Wu (2013) for example.

Honnert et al. (2016) modified a mass-flux scheme for the CBL gray zone (Pergaud et al., 2009), by generalizing the mass flux equations without the need for assumptions that the vertical velocity in the grid cell is zero or that the thermal fraction is negligible. In this framework, the velocity of the parameterized updraft is reduced when the resolution increases, which then permits the model dynamics to produce resolved struc-

tures. The study also incorporates a dependency on the normalized resolution $\Delta x/(z_i + z_c)$ in the surface closure conditions, as discussed further by Lancz et al. (2017).

Shin and Hong (2015) have proposed a one-dimensional parameterization for the CBL gray zone based on Eq. 9, but which gradually reduces the parameterized vertical transport as model resolution increases. The local transports from small-scale eddies and the sub-grid non-local transports are computed separately and reduced at different rates. The non-local transport is formulated from three linear profiles which capture its three most important roles: surface-layer cooling, mixed-layer heating, and entrainment at the CBL top of air from aloft. Each of these profiles is constructed as a function of stability parameters in the surface- and/or entrainment layers. The method is designed to reproduce the total non-local turbulent transport, and the required sub-grid portion is computed by multiplying an explicit grid-size dependent function which can also vary according to the transported variable, the height (Honnert et al., 2011), and the stability (Shin & Hong, 2013). The local transport is formulated as an eddy diffusivity, and is multiplied by a different grid-size dependent function (Shin & Hong, 2015). Both idealized and real-case simulation results with the CBL gray-zone parameterization showed improvements over the use of the conventional unmodified parameterization at CBL gray-zone resolutions.

Such changes, however, do not solve all the problems of the gray zone of turbulence. The modified mass-flux, for example, remains based on horizontal homogeneity assumptions. Thus, it should be coupled with a local turbulence scheme that is itself adapted to the CBL gray zone, especially over mountains where it does not produce enough turbulent transports and can lead to unrealistic vertical velocities.

As noted in Section 1.2, the UK Met Office runs operational forecasts at gray zone scales of 1.5 km and 333 m. Particularly in the latter case some of the large eddies responsible for much of the transport are resolved, but other turbulent motions are partially or completely unresolved and continue to require some non-local parameterization. The approach has been to devise a pragmatic blending between mesoscale and LES parameterizations (Boutle et al., 2014). The former is provided by the Met Office boundary layer scheme (Lock et al., 2000) (which is similar to Eq. 9 for a CBL) and the latter by a 3D Smagorinsky (Eq. 7) scheme. The blending is scale-dependent, being based on the ratio of the grid scale to a diagnosed length scale characterising the turbulence. The benefits of this blended parameterization in the UM are well illustrated by Boutle et al. (2014), where a realistic stratocumulus case was simulated using horizontal grid lengths from 100 m to 1 km, the turbulence changing from largely resolved to largely unresolved. However, the diffusive nature of the Smagorinsky scheme can result in the delayed spin up of non-local motions especially during the handover from the non-local mesoscale to the Smagorinsky scheme in deepening CBLs, as shown in Efstathiou et al. (2016). Efstathiou and Plant (2019) extended the blending approach by incorporating a scale-dependent dynamic Smagorinsky scheme instead of the standard static Smagorinsky scheme. They found some promising results in idealized simulations of an evolving CBL, particularly in relation to the spin-up of resolved turbulence (cf. Section 3.3.2).

3.5 The gray zone of turbulence as a Rayleigh-Bénard convection problem

Zhou et al. (2014) examined the grid-dependent nature of gray-zone CBL simulations using a mesoscale parameterization of turbulence. The analysis is based on the Rayleigh-Bénard (RB) thermal instability framework, with the Rayleigh number (Ra) redefined by its turbulent counterpart

$$Ra = -P_{rT}\frac{N^2 H^4}{{\nu_T}^2}, \tag{11}$$

where P_{rT} is the turbulent Prandtl number, N (s^{-1}) is the buoyancy frequency, ν_T ($m^2 s^{-1}$) is the eddy viscosity, and H (m) is a length scale over which N is computed. H scales with the boundary layer depth z_i (m). It is set to the surface layer depth (about 0.1 z_i) in Ching et al. (2014), and to z_i in Zhou et al. (2014). In extending the RB analysis to the CBL, the effects of wind shear, which are mostly concentrated in the surface layer and the entrainment zone, are ignored. Turbulent mixing terms are also linearized by assuming an eddy-diffusion representation. Despite its simplicity, the RB framework is useful for understanding model behaviors associated with conventional ABL schemes acting on CBL gray zone grids. For example, the onset of convection in the resolved flow was explained based on the RB framework. The onset depends on a critical value of Ra which is itself a function of grid spacing in the CBL gray zone. Sufficient instability in the surface layer eventually leads to strong grid-scale convection after Ra has reached its critical value.

The turbulent nature of grid-scale convection can mask mesoscale circulations, such as a well-defined sea breeze. Ching et al. (2014) drew on the Rayleigh-Bénard framework to develop a scheme based on the Rayleigh number which aims to suppress any convective motions in CBL gray zone simulations. Specifically the thermal diffusivity was modified in order to keep Ra below its critical value and so convective overturning remained as a sub-filter process even at very fine grid lengths. This stands in contrast to the other methods discussed in this paper.

3.6 Stochastic approach

As discussed in Section 2.4, scale adaptive modeling of transport in the boundary-layer gray zone is intrinsically linked with representing stochastic behavior. Stochastic backscatter techniques have a well-established value in improving LES simulations close to the earth's surface. The length scale of the dominant eddies close to the surface is constrained by the presence of the surface, so that $l \sim z$. It follows that the near-surface flow may lie within the turbulence gray zone of $l \sim \Delta$ even for situations in which the turbulence in the interior of the flow is well resolved (Mason & Thomson, 1992; Weinbrecht & Mason, 2008). The backscatter of energy from unresolved scales onto the grid can improve turbulent statistics in such cases and has also proved helpful in the *near gray zone*. A recent extension by O'Neill et al. (2015) allows for grid-independent spatial variations in the backscatter rate.

An important issue in the performance of gray-zone turbulence parameterizations, as alluded to several times above, is a mechanism to initiate resolved-scale turbulent structures in an evolving flow. In reality turbulent length scales might be growing from sub-grid to resolved scales but as the simulated growth may be overly slow, the explicit inclusion of some local near-grid-scale variability can prove useful. Backscatter, and other stochastic methods, can provide such mechanisms. (An alternative may be to make the low-level temperature profile unrealistically unstable by, for example, suppressing the non-local flux, as shown in Efstathiou and Beare (2015).) The issue is most often discussed in terms of the spin-up of resolved turbulence in time from an initial smooth field. However, similar issues also arise in transitioning to resolved turbulence downstream of the smooth lateral boundary conditions that are usually imposed in numerical weather prediction. Lateral boundary spin-up has received less attention in the literature to date, but we note that some methods addressing the problem have been developed in the engineering community, involving the injection of synthetic turbulence (e.g. Xie & Castro, 2008) and these ideas may provide a suitable remedy.

Various stochastic parameterization approaches have been developed for climate models and ensemble-based numerical weather prediction as modifications to mesoscale parameterization methods. To date, these have often been focused on the parameterization of diabatic processes, especially deep convection, and reviews of such techniques

are provided by Khouider et al. (2010); Palmer (2012) and Plant et al. (2015). Some of these ideas may also be applied in the CBL gray zone. Simple methods have included rescaling the parameterization tendencies by a random multiplicative factor or making random choices for some of the scheme parameters (Palmer, 2001). Alternatives have attempted to embed stochastic variability at a deeper level, within the sub-grid process description. A suitable starting point is to partition the total turbulent flux into contributions from multiple transporting elements, which may include information about size. Grid-scale adaptivity can then be achieved by size-filtering the population (Brast et al., 2018), while stochasticity can be represented in the element properties. A natural choice is to consider that a random number of elements may be found within a grid area (Leoncini et al., 2010; Plant & Craig, 2008) while others allow LES-informed random switching between distinct modes of turbulent heating (Dorrestijn et al., 2013) or random variability in the element/environment mixing rate (Suselj et al., 2014). The variables for which suitable spectra of elements have been constructed include the local thermodynamic state (Cheinet, 2003; Neggers et al., 2002, 2009), the mass flux carried by the elements (Plant & Craig, 2008; Sakradzija et al., 2014, 2016), or even size itself (Neggers et al., 2019; Park, 2014; T. M. Wagner & Graf, 2010).

A simple stochastic method has been implemented operationally in the Met Office UM turbulence-gray-zone configurations which draws on some of the above ideas. It can be considered as a simplified stochastic backscatter scheme where random boundary-layer temperature and humidity perturbations are applied to the smallest resolvable scale (taken to be 8 grid-lengths). The magnitude of the perturbations are designed to represent realistic boundary layer variability that would arise from a variety of poorly resolved processes at km-scale (not just boundary layer thermals but also surface heterogeneities and convection). The scheme also includes a time correlation of the perturbations on an approximate large-eddy turnover time scale. At present no attempt has been made to make these perturbations scale in a physically appropriate way, e.g. with the relative scale of the boundary-layer eddies to model resolution. Overall the scheme gives significant improvements to the initiation of small diurnally triggered convective showers over the UK and also improves spin-up of convective scale motions from the boundaries. Some other related approaches for introducing physically-based boundary-layer fluctuations are described by Muñoz-Esparza et al. (2014); Kober and Craig (2016); Leoncini et al. (2010).

Kealy et al. (2019) examined in more detail the impact of random boundary layer temperature perturbations on the spin-up of resolved turbulence at gray-zone resolutions. They found that the combination of imposed perturbations along with a scale-dependent sub-grid turbulence scheme has the most pronounced effect on the spin-up of resolved motion.

3.7 Grid refinement approach

Zhou et al. (2017) have proposed a rather different modeling methodology for CBL gray-zone simulations, based on refining the horizontal grid spacing in the surface layer (the bottom 10-15%). They adopt a two-way nesting technique to couple the simulation of the surface layer with that in the rest of the CBL. Since thermals in the CBL originate from the surface layer, the idea is that an improved representation of the surface layer should induce a good representation of the thermal population throughout the CBL. An LES turbulence closure is used in the surface layer and a mesoscale form of parameterization is adopted aloft. Zhou et al. (2018) demonstrate results which show substantial improvement of first and second order turbulent statistics, especially when horizontal resolution is refined up to half of the CBL depth (Zhou et al., 2017).

The grid refinement approach should be considered as a numerical method rather than a parameterization. In the high-resolution surface nest, assumptions behind ABL

schemes are completely replaced by traditional LES assumptions (i.e. inertial sub-range grid spacing and isotropic sub-grid turbulence). The grid refinement method does not really differentiate grid spacings aloft, and can be applied as a general nesting method. The method is of limited use to LES because the turbulent flows are already well resolved in the CBL, although Sullivan et al. (1996) and Huq et al. (2014) did apply a similar method with LES as an improved wall model to better resolve fine-scale surface-layer turbulence. The method is also unnecessary for mesoscale models, because however well resolved the thermals are in the nested high-resolution surface grids, they are not expected to have any impact on the coarse mesoscale grids where they are entirely subgrid-scale.

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3.8 Summary and critical review

Section 2 discusses the major challenges of modeling in the CBL gray zone. In the LES regime, the subgrid-scale turbulence is small, homogeneous and isotropic. At the near gray-zone, turbulence starts to become anisotropic (Section 2.4) and the possibility of some resolved-scale turbulence (Section 2.1) is a challenge, not least in producing spin-up problems. In the gray-zone regime, the horizontal homogeneity hypothesis, usually used at mesoscales, is no longer valid (Section 2.4) and CBL thermals that are entirely subgrid at the mesoscale (Section 2.2) are partly resolved. Figure 8 summarizes the different regimes and the validity domains of the different parameterizations.

The experiences of performing CBL gray-zone simulations with conventional (LES or mesoscale) parameterizations show that models are likely to fail to capture a correct resolved turbulence or else to produce unrealistic over-energetic turbulent structures (Honnert et al., 2011). The behavior of models in the gray zone of turbulence depends on various physical factors (surface characteristics, topography, and time of day, among others) and also on the model specifications (such as the grid spacing, the diffusion, numerical damping, etc). Moreover, the model grid spacing itself can be a poor proxy of the actual model resolution (Ricard et al., 2013; Skamarock, 2004). In particular, the gray zone of turbulence cannot be limited to the hectometric scales: gray-zone issues can impact on modeling at both larger (Goger et al., 2018) and finer scales (Wyngaard, 2004).

Nonetheless, there does seem to be a critical core of new ideas emerging that is well worth pursuing in sub-kilometer simulations. No parameterization is created ex nihilo. Historically, LES and mesoscale schemes have drawn upon assumptions and simplifications that are informed by our understandings of the atmospheric boundary layer. For instance, most mesoscale schemes assume that turbulent fluxes are horizontally homogeneous so that only the vertical flux needs to be parameterized. On the other hand, most LES schemes assume that sub-grid turbulence is isotropic. The subgrid flux is characterized by a single mixing length when an eddy viscosity model is employed.

Figure 8 shows two categories of scheme. One category treats the gray zone of turbulence by starting from mesoscale approaches and attempt to adapt and extend them for higher resolution applications (mass-flux modifications and Shin and Hong (2015), RB representation and most of the stochastic parameterizations). These schemes typically aim to reduce the non-local subgrid turbulence, but remain focused on a vertical 1D representation of the CBL. Some of these schemes operate by blending LES and mesoscale formulations, including the two turbulence kinetic energy approach (Bhattacharya & Stevens, 2016) and the blended model of (Boutle et al., 2014). The blended approaches seem able to produce scale-adapted subgrid CBL thermals, as well as LES isotropic turbulence when necessary. However, there is as yet no good evidence that they can capture the anisotropic character of the turbulence in the near gray zone regime. The incorporation of additional

c1 *Rev.1*: The section number has changed

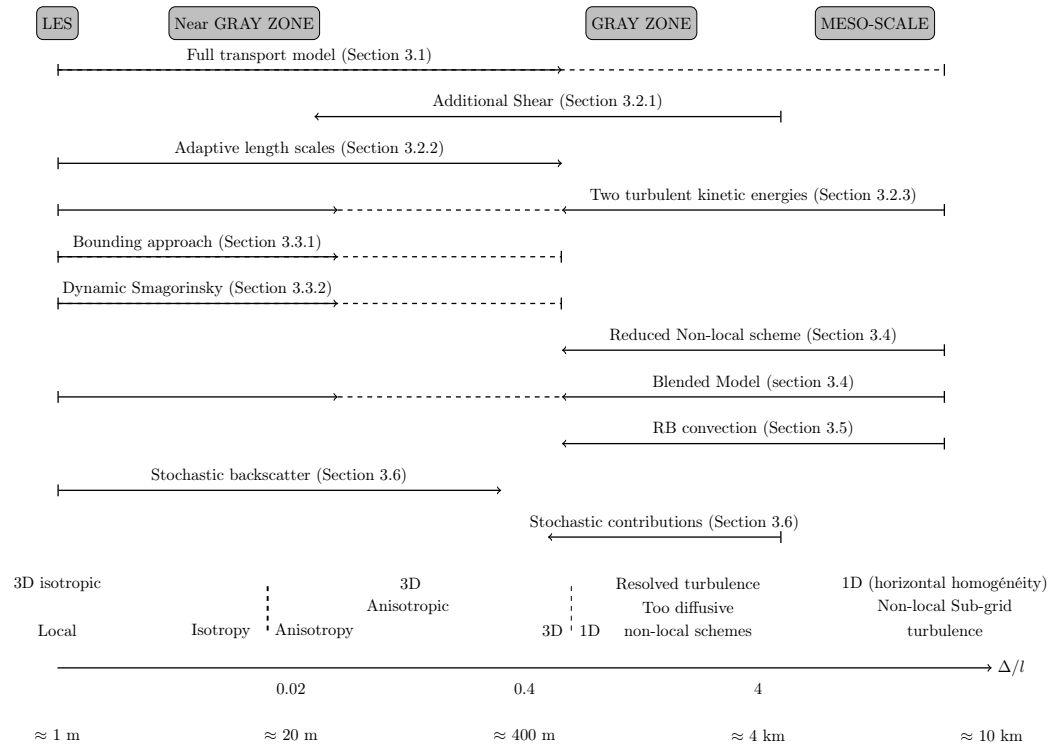

Figure 8. Schematic summarizing the relations between the various approaches that have been introduced and discussed. To simulate the turbulence in the gray zone, each method has a starting point in LES or mesoscale model and to a certain extent gets rid of the initial hypotheses. [c3]The dotted line shows where a parameterization family has no theoretical limit, but no application yet.

wind shear terms in a TKE scheme, as in (Goger et al., 2018), may compensate for the lack of 3D turbulence in the gray zone, but it does not produce the limiting forms of behavior of 1D CBL thermals at the mesoscale or a 3D isotropic scheme in LES. The other major category attempts to treat the gray zone of turbulence as essentially "coarse LES" by adapting and extending LES turbulence models into the gray-zone regime (full transport model, all adaptations of the mixing length, bounding model and dynamical Smagorinsky). Such schemes have had some successes, especially in extending from the LES, isotropic, mainly-resolved turbulence regime into the near gray-zone anisotropic-turbulence region, but they cannot represent non-local turbulence typical of the CBL at the mesoscale.

Although most of the parameterizations that have been developed so far cannot be seamlessly used from LES to the mesoscales, they do provide some interesting clues towards solving practical problems in the gray zone of turbulence. Some promising results have emerged from both major categories. Some simple blending/hybrid schemes using non-local turbulence (Boutle et al., 2014; Efstathiou & Plant, 2019; Shin & Hong, 2015), TKE (Ito et al., 2015; Zhang et al., 2018) or mass-flux approaches (Honnert et al., 2016) may significantly improve the representation of first-order quantities and turbulence statistics in the CBL gray zone.

4 Discussions

Modeling within the CBL gray zone is increasingly becoming seen as necessary for near future operational use because there is a growing demand for higher resolution forecasting, especially for the prediction of high-impact weather events. A wide range of novel approaches have been presented (Section 3) in this article incorporating various new parameterization ideas to address the challenges of the CBL gray zone. Moreover, an increasing number of researchers are actively working on the topic. Thus, the turbulence gray zone has clearly become a hot topic in atmospheric modeling. However, key questions remain.

4.1 Is the gray zone of turbulence stalling the improvement of atmospheric modeling?

Our review has shown that most of the gray-zone turbulence studies to date have been based on idealized or real but relatively simple well-known cases over homogeneous surfaces (e.g. the Wangara case study). Some caution is therefore needed. In order to develop atmospheric modeling we require not just that there is an appropriate treatment of turbulent motions in the gray zone but also that their treatment should enable the correct interactions with other atmospheric processes. These points are discussed in Section 2.6 and are highlighted by LeMone et al. (2010) or J. S. Wagner et al. (2014) for example. However, there are also well-documented cases that clearly benefit from improving resolution into the gray zone of turbulence, despite potential issues with sub-grid scale turbulence parameterization. This can be seen in the simulations of Warren et al. (2014) for a slow-moving organized convective system over a complex terrain area in southwest England.

Most scale-aware gray-zone schemes for the CBL have been developed with a focus on cloud-free conditions or with shallow cumulus clouds. It is much less clear how many of the schemes would perform in deep moist convection environments, including organized systems or tropical cyclones. It is also less clear how they might couple to synoptic-scale motions (Section 2.6). A useful study from this perspective is that of Green and Zhang (2015) who investigated the partition between resolved and sub-grid turbulent fluxes in turbulence gray-zone simulations of hurricane Katrina. In their simulations, the partitioning and the character of the resolved turbulent structures varied significant with the resolution, but the system's intensity was not affected because the total turbulent

fluxes remained almost the same. Other case studies of other phenomena with other approaches to the gray zone of turbulence would clearly be valuable.

The complexity of partially-resolved structures in the gray-zone boundary layer and the feedbacks between resolved and sub-grid dynamics during deep convective cloud development are not yet understood. Pronounced sensitivity to turbulent mixing in sub-kilometer simulations of deep convection has been identified in a number of recent studies. Verrelle et al. (2015) showed that insufficient mixing led to strong undiluted thermals and unrealistic resolved TKE in a super-cell simulation. In Hanley et al. (2014), simulated deep clouds were found to exhibit small features compared to radar observations, although their representation could be somewhat improved by increasing the sub-grid turbulence mixing length. Moreover, Verrelle et al. (2017) identified the presence of non-local structures in deep clouds that can pose significant challenges to conventional mixing schemes. Ito et al. (2017) examined a number of heavy rainfall cases and found that the rate of improvement in the skill of the forecasts became progressively smaller for further increases of horizontal resolution into the sub-kilometric regime. Although their simulations seemed to be relatively insensitive to the CBL representation, the results do indicate that interactions of the near-grid scale with the larger scale environment, and with other processes, might still be important in the gray zone of turbulence.

An important context for these findings is the resolution required for the representation of deep convective clouds. There is a convective gray zone associated with such clouds at grid spacings of around $1 - 10$ km. So called "convection permitting" simulations with the convection parameterization switched off have been shown to yield some significant benefits for $\Delta x < 5$ km (Roberts & Lean, 2008). However one would not expect the deep clouds to be well represented on a numerical grid unless one can adequately resolve the turbulent mixing processes at the cloud edges. These have a scale of ~ 100 m (Craig & Dornbrack, 2008), so improvements in modeling explicit deep convection might prove modest until those grid lengh scales are reached, *unless* a better parameterization of turbulent mixing processes can be introduced.

As illustrated by Stirling and Petch (2004) and Kealy et al. (2019), the impact of small-scale boundary-layer variability is important for an accurate representation of the diurnal cycle of convection in the turbulence gray zone, not least for the timing of deep cloud initiation. This point encourages further development of stochastic approaches and improvement can reasonably be anticipated from imposing appropriate small-scale variability in the CBL.

4.2 Should resolved convective motion be allowed in the turbulence gray zone?

Ching et al. (2014) argue that any partly-resolved turbulent motions in gray-zone ABL simulations are not realistic and should be damped. Since the simulations are not in the LES converging regime and the results depend heavily on the imposed dissipation, they should not be trusted. Hence, these authors pursue an ensemble-average approach to the model filter operation, in which their gray-zone ABL simulations are valued for producing improved numerical accuracy for a mesoscale modeling approach (cf. Mason & Brown, 1999). The authors showed an example of noisy resolved motions that masked the lake-breeze field. However, they do recognize the importance of resolved convective structures in the CBL for the triggering of deep convection, as discussed in the previous subsection.

The initiation of resolved motion in gray-zone ABL simulations is generally considered to be a valued aspect for the majority of gray-zone ABL studies and for operational atmospheric models. By allowing some partially-resolved convective overturning motion, most modelers are (conceptually at least) following a spatially-filtered approach in which an *appropriate* level of variability near to the filter scale is considered

to be desirable. It should be stressed that this is also the view taken by coarse-graining studies and in simulation strategies developed from those.

4.3 Testing models in a realistic set-up - The Gray Zone Project

The Gray Zone Project promotes international collaborations and community activities in the development of scale-aware deep and shallow convection and boundary-layer parameterizations and focuses on grid lengths of about 200 m to 10 km. It has been initiated by WGNE (Working Group on Numerical Experimentation) and the GEWEX (Global Energy and Water Exchanges) Global Atmosphere System Studies.

A first phase of the Gray Zone Project examined the simulation of a maritime cold air outbreak that was observed during a field campaign (Field et al., 2014). Model intercomparisons have been reported for simulations with global models (Tomassini et al., 2016), limited-area models Field et al. (2017) and large-eddy simulations (de Roode et al., 2019). Model resolutions were systematically varied in order to explore their behaviors across a range of spatial scales, and results were compared to the observations. A second phase of the project is now being planned and will investigate shallow cumulus clouds at turbulence gray-zone resolutions as part of the EUREC4A project in 2020 (Elucidating the role of clouds-circulation coupling in climate, Bony et al., 2017) and also the transition from shallow to deep convective clouds over the eastern tropical Atlantic based on the GATE field campaign (Global Atmospheric Research Program's Atlantic Tropical Experiment, Kuettner, 1974).

4.4 Prognostic adaptive schemes the way forward?

Most proposed methodologies in the boundary-layer gray zone have either LES or mesoscale parameterizations as their starting point. However, various mesoscale parameterizations based on prognostic equations do exist (e.g. Lappen & Randall, 2001; Tan et al., 2018), and since these tend to be more adaptive to the resolved flow, they may be worth more attention in terms of developing extensions for the gray zone of turbulence. Such mesoscale parameterizations are often designed with an assumption that the thermal fraction is assumed small, which is a defect in the gray zone of turbulence. Modifications such as those in Honnert et al. (2016) to introduce a scale-aware thermal area fraction may therefore be necessary in extending their use. A related starting point could also be that of Thuburn et al. (2018), who recently proposed a two-fluid theoretical framework for the representation of convection in models, using coupled prognostic primitive equations for both the coherent eddy structures (convective plumes) and their environment.

An approach that seems to be able to bridge the gap between the LES and the mesoscale limits, is the full transport model of Wyngaard (2004). Nevertheless, solving several prognostic higher-order equations, involving several terms that require further closure assumptions and parameters, can be computationally expensive. Linear algebra closure models such as Lazeroms et al. (2016) could offer a potential route forwards to reducing computational costs while retaining the tensor representation of the fluxes that is at the core of the approach. In either case, the dynamic modeling technique of filtering at multiple scales (Bou-Zeid et al., 2005; Chow et al., 2005) can be used to determine the necessary length scales and tuning parameters, thereby making such schemes not only scale-aware but also flow-dependent. Dynamic calculation of length scales in an evolving CBL has been shown to be beneficial for the CBL gray zone (Efstathiou et al., 2018; Efstathiou & Plant, 2019).

It is clear that special care needs to be taken in the gray zone of turbulence for the representation of horizontal fluxes (Zhou et al., 2017). The conventional 2D Smagorinsky adaptation for horizontal mixing has been shown to be inappropriate in the repre-

sentation of CBL mixing (Ito et al., 2014; Zhou et al., 2017). A recent scale-aware representation of horizontal diffusion from Zhang et al. (2018), based on Honnert et al. (2011) and using the blending approach of Boutle et al. (2014), has shown promising results.

5 Conclusions

We have reviewed the current state of a newly-emerged research area in the numerical modeling of geophysical flows and discussed the significant challenges that arise for the atmospheric modeling community. Numerical models are now moving towards sub-kilometer grid spacings at which they produce partially-resolved turbulent structures. As a result in the "gray zone" of turbulence, the fundamental assumptions underpinning our conventional treatments of sub-grid scale variability are no longer valid. Furthermore, at CBL gray-zone resolutions the resolved scale variability becomes highly dependent on the representation of sub-grid motion that in turn can compromise the accuracy and value of the numerical model simulations.

A model's horizontal grid spacing cannot by itself determine the onset of the CBL gray zone or explain the transition of the TKE and heat and moisture fluxes from the LES to the mesoscale limit. The key to describing the transition is to consider the relative extent of the dominant turbulence length scales compared to the effective grid spacing. This means that different structures, whether these are CBL thermals or clouds at the top of the ABL, might be in different resolution regimes especially as they evolve over time (similar to Fig. 6). It also means that one should take into account the imposed dissipation from the numerical methods in use, which can damp or smooth the resolved field. The interplay of numerical and "physical" diffusion (from the turbulence parameterization) will determine the effective resolution of an atmospheric model; i.e. its ability to partially resolve features at the limits of its grid resolution (Skamarock, 2004).

The proposed gray-zone CBL parameterization schemes in the literature, as presented here, are largely based on two approaches: treating the gray zone of turbulence as either a coarse LES or a high-resolution mesoscale model depending on the starting point of each parameterization. However, there are some approaches that attempt to avoid the bulk of the gray zone of turbulence, either by increasing the horizontal resolution in certain parts of the CBL or by filtering out any turbulent motions. The latter approach considers the simulation to belong the mesoscale resolution regime where all of the turbulent transfer is parameterized in an ensemble-average sense. Even though many of the schemes considered show certain merits and benefits in the gray zone of turbulence, most of them have been tested in idealized settings. As a next step more comprehensive studies are needed using realistic case studies to identify the interactions of partially-resolved turbulent mixing with deep convective clouds and with the larger scale circulations.

The full turbulent transfer equations should, at least in principle, be able to handle the transition of turbulent transfer from well resolved to fully parameterized. However, solving the full turbulent transport equations would be computationally expensive and suitable closure assumptions would be needed, perhaps depending on the level of information that is available from the resolved motions. As this approach may not be practical, even with the available computing power, the anisotropic production terms in the transport equations might be usefully retained in various simplified ways.

It is very clear that the existence of the turbulence gray zone has important implications and consequences for atmospheric modeling and for the future of numerical weather prediction in particular. Recent studies, such as those discussed in Section 4, have demonstrated that at sub-kilometer grid spacings increasing convergence with increasing grid resolution is not guaranteed, especially in simulations with deep convection. However, the full extent of the impact of partially resolved turbulent flow on the actual performance of weather forecasting needs to be further investigated. This is partly

due to the fact that some of the feedbacks between the turbulent mixing in the CBL and synoptic-scale systems are not yet well understood. Nevertheless, the refined resolution can still prove to be beneficial, especially when it is combined with better representation of topography and surface heterogeneity and especially in cases with strong large-scale forcing.

Although this article has been focused on the CBL gray zone and atmospheric simulations, other aspects of geophysical fluid flow modeling experience their own gray zone. The representation of any important physical phenomenon with a length scale of the same order as the grid spacing is liable to be problematic in numerical simulations. Such a situation is clearly undesirable but sometimes cannot be avoided, due to finite computational limitations or else because the phenomenon itself covers a range of scales. The CBL gray zone is *relatively* simple in various respects, the dominant turbulent structures being well understood and having a well-defined length scale dictated by the CBL depth. Thus, it provides a good base case for the study of possible methods for treating gray zone motions in geophysical flows more generally. Promising approaches to gray zones may be more easily identified in this setting, and conversely, it seems difficult to imagine that approaches performing poorly for the CBL gray zone would somehow work well in other, more complex settings.

Appendix A The full transport equations

In Section 3.1 a tensor form of the eddy diffusivity was presented. Following Wyngaard (2004), this may be derived from the scalar-flux transport equation. The sub-grid flux of a conserved scalar field c in the i direction is denoted $f_i = \overline{cu_i} - \overline{c}\,\overline{u}_i$ where the overbar is a spatial filter, and it evolves as (Wyngaard, 2004):

$$\frac{\partial f_i}{\partial t} + \overline{u}_j \frac{\partial f_i}{\partial x_j} = -f_j \frac{\partial \overline{u}_i}{\partial x_j} - \tau_{ij} \frac{\partial \overline{c}}{\partial x_j} + \mathrm{PT} + \mathrm{FLXDIV}, \tag{A1}$$

The first two terms on the right hand side are production terms, the first (tilting term) representing the stretching and "tilting" of turbulent eddies and the second representing the interaction of turbulent fluxes (Reynolds stresses, τ_{ij}) with the scalar gradient (gradient term). Other terms express the pressure – scalar interactions (PT) and the divergence of the sub-grid flux of f_i (FLXDIV). The flux divergence terms contain higher order contributions that express the sub-grid turbulent transport of f_i. PT acts as a principal sink for the scalar flux and can be parameterized as $-f_i/T$ in its simplest linear form, with T representing a characteristic time scale of the sub-grid turbulence.

Wyngaard (2004) proposed a model for the sub-grid scalar fluxes that is obtained by retaining the first two production terms in Eq. A1, assuming a steady state, and balancing the production with the pressure terms. The model is given by:

$$f_i = -T \left(f_j \frac{\partial \overline{u}_i}{\partial x_j} + \tau_{ij} \frac{\partial \overline{c}}{\partial x_j} \right). \tag{A2}$$

Although Eq. A2 expresses an algebraic model, it would be entirely straightforward to retain a prognostic form based on Eq. A1.

Dropping the tilting terms and retaining only the gradient production terms in the direction of the flux (isotropic gradient production), Eq. A2 reduces to:

$$f_i = -T\tau_{ii} \frac{\partial \overline{c}}{\partial x_i} = -K_c \frac{\partial \overline{c}}{\partial x_i}. \tag{A3}$$

This corresponds to the down-gradient diffusion model that is commonly used as a basis for turbulence parameterization in both LES closures and mesoscale ABL schemes. $K_c = T\tau_{ii}$ is the eddy diffusivity. Without these additional assumptions, the formal so-

lution of Eq. A2 is given by Eq. 2 (Wyngaard, 2004):

$$f_i = -K_{ij} \frac{\partial \overline{c}}{\partial x_j} \tag{A4}$$

where K_{ij} is a tensor form of the eddy diffusivity which is a function of T, the shear tensor $\partial \overline{u}_i / \partial x_j$ and τ_{ij}.

Glossary

Atmospheric Boundary layer The bottom layer of the atmosphere that is in contact with the surface of the earth.

Free Troposphere The part of the Earth's troposphere which excludes the boundary layer. Turbulence in the boundary layer is ubiquitous but in the free troposphere is produced only sporadically, by mechanical forcing in regions of pronounced wind shear or thermally inside convective clouds.

Backscatter Energy transfers in turbulent three-dimensional fluid motions occur to both larger and smaller spatial scales. The net transfer within the inertial subrange is downscale but the backscatter refers to the upscale component of energy transfer, from subgrid-scale to resolved motions.

Baroclinic waves Synoptic-scale disturbances that grow in the mid-latitudes due to baroclinic instability and which are responsible for the development of weather systems.

Deep Clouds Clouds with predominantly vertical development that form as a result of deep convection in the troposphere. They may extend from the top of the boundary layer towards the upper troposphere (cumulus congestus) or as far as the tropopause (cumulonimbus). Such clouds may be associated with thunderstorms, heavy rainfall and hail.

Large-Eddy Simulation A three-dimensional numerical simulation of turbulence, in which the largest eddies are explicitly resolved, while the effects of subgrid-scale eddies in the inertial subrange are parameterized.

Large/synoptic-scale The scales of the general atmospheric circulation related to the high-tropospheric long-wave patterns.

Low-level jet A jet of wind that appears in the boundary layer.

Mesoscale Refers to atmospheric phenomena having horizontal scales ranging from a few to several tens of kilometers, including thunderstorms, squall lines and topographically-induced circulations such as mountain waves, mountain and valley breezes as well as sea and land breezes.

Parameterization The representation, in a dynamic model, of physical effects in terms of admittedly oversimplified parameters, rather than realistically requiring such effects to be consequences of the dynamics of the system (from American Meteorological Society Glossary).

Shallow Clouds Low-level, usually non-precipitating, clouds which may be considered to form part of the ABL. Cumulus and stratocumulus are forms of shallow convective clouds.

Troposphere That portion of the atmosphere where most weather occurs and which extends from the Earth's surface to a sharp temperature inversion at the tropopause, between 10 and 20 km aloft.

Surface Layer The lowest 10–15% of the atmospheric boundary layer where first order quantities such as wind and temperature follow an approximately logarithmic profile and turbulent fluxes may be considered almost constant.

Non-local turbulence A term used in the context of 1D mesoscale parameterizations to refer to coherent turbulent structures that typically extend to the full depth of the turbulent layer. In the CBL, non-local turbulence is associated with buoyant thermals.

Acronyms

ABL Atmospheric Boundary Layer
CBL Convective (Atmospheric) Boundary Layer
COSMO COnsortium for Small-Scale Modeling
GEWEX Global Energy and Water Exchanges Global
LEM Met Office Large Eddy Model
LES Large Eddy Simulation
MYNN Mellor-Yamada-Nakanishi-Niino model
NWP Numerical Weather Prediction
RB Rayleigh-Bénard
TKE Turbulent Kinetic Energy
VLES Very Large-Eddy Simulation
WGNE Working Group on Numerical Experimentation
WRF Weather Research and Forecasting

Notation

$\boldsymbol{c}$ a conserved scalar.
$\boldsymbol{c_u}$ value of c inside the mass-flux thermal plume
$\overline{\boldsymbol{c}}$ mean value of c
$\boldsymbol{C_c}$ a constant value for a given scalar c
$\boldsymbol{C_s}$ Smagorinsky coefficient
$\boldsymbol{\Delta}$ grid spacing, model resolution
$\boldsymbol{\Delta x}$ model horizontal grid spacing
$\boldsymbol{\Delta z}$ model vertical spacing
$\boldsymbol{e}$ TKE
$\boldsymbol{e_{\mathbf{sgs}}}$ subgrid-scale TKE
$\boldsymbol{e_{\mathbf{res}}}$ resolved TKE
$\boldsymbol{e_{\mathbf{tot}}}$ total (resolved plus subgrid-scale) TKE
$\boldsymbol{f_i}$ sub-grid scalar flux
$\boldsymbol{\gamma}$ counter-gradient term
$\boldsymbol{H}$ a length scale over which N is computed
$\boldsymbol{k}$ wave number
$\boldsymbol{k_{d,\mathbf{eff}}}$ dissipation wave-number in Beare (2014)
$\boldsymbol{k_d}$ dissipation wave-number
$\boldsymbol{k_0}$, $\boldsymbol{k_1}$ wave-number limits in Beare (2014)
$\boldsymbol{K_c}$ the eddy diffusivity associated with the conserved variable c
$\boldsymbol{K_{ij}}$ a tensor form of the eddy diffusivity
$\boldsymbol{l}$ length scale of the dominant energy containing structures
$\boldsymbol{l_m}$ mixing length used in a TKE based parameterization
$\boldsymbol{l_t}$ Smagorinsky mixing length scale
$\boldsymbol{l_d}$ dissipation length scale
$\boldsymbol{\nu_T}$ the eddy viscosity
$\boldsymbol{M_u}$ mass-flux of ABL thermals
Pr Prandtl number
$\boldsymbol{P_{rT}}$ turbulent Prandtl number
Ra Rayleigh number
$\boldsymbol{\tau_{ij}}$ Reynolds stress
$\boldsymbol{S_e}$ TKE power spectrum
$\boldsymbol{T}$ time scale for sub-grid turbulence

$\boldsymbol{\theta}$ potential temperature
$\boldsymbol{u}$ a wind component
$\boldsymbol{w}$ vertical velocity
$\boldsymbol{z_c}$ depth of the cloud layer
$\boldsymbol{z_i}$ CBL height
$\boldsymbol{z}$ altitude

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This article is a review paper : Data were not used, nor created for this research

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